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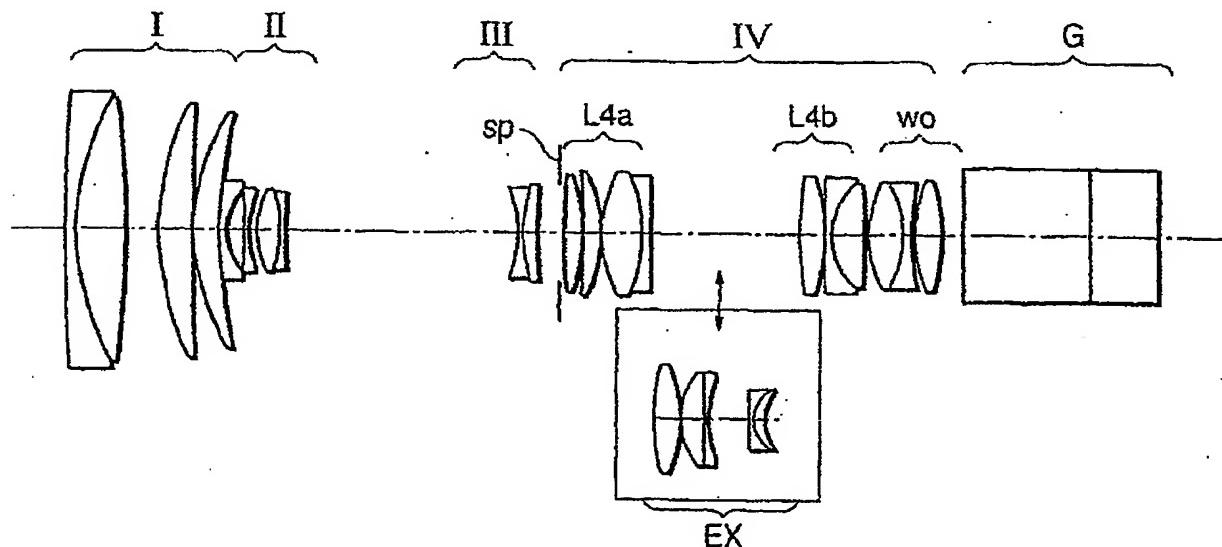
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(54) Zoom lens and photographing system

(57) Four-unit zoom lens in/from which a magnification changing optical unit for changing the overall focal length of the zoom lens can be inserted/removed, wherein a wobbling unit, which can be slightly ampli-

tude-driven in the optical axis direction to detect the best imaging position, is placed in the fourth unit closer to the image than the position at which said magnification changing optical unit is inserted/removed.

FIG. 1



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Description**BACKGROUND OF THE INVENTION****5 Field of the Invention**

[0001] The present invention relates to a zoom lens suitable for a TV camera, video camera, and the like.

10 Related Background Art

[0002] As an autofocus (AF) system in a video camera or the like, a system called "hill-climbing AF" which obtains the distance to a principal object and drives a focus unit to an appropriate position is widely used.

[0003] In this system, the direction of the best imaging position is detected from a change in a video signal by using some of the lens units of an image pickup system for imaging, and the extension direction of a focusing lens is calculated.

15 A merit of this system is that no optical system need be newly used for distance measurement.

[0004] In addition, in this system, in order to check whether the best imaging position is located before or after the image pickup surface (CCD surface or film surface), a partial optical system of the image pickup system is slightly amplitude-driven (to be referred to as wobbled hereinafter) in the optical axis direction. A focus unit is driven to set the best focus on the image pickup surface on the basis of the detected signal.

20 [0005] At this time, since part of the optical system is wobbled, the imaging magnification greatly changes to result in poor screen display unless lens units and the like are properly arranged.

[0006] As a method of reducing a change in imaging magnification, the method disclosed in Japanese Patent No. 2744336 is available. This method is associated with a rear focus zoom lens which has the first unit having a positive refractive power, the second unit having a negative refractive power for magnification changing operation, the third unit having a positive refractive power, and the fourth unit having a positive refractive power and serving to correct an image plane fluctuation with a change in magnification, and is designed to perform focusing by using the fourth unit.

25 [0007] A change in imaging magnification accompanying wobbling can be expressed by a paraxial trace. Several conditions for suppressing a change in imaging magnification accompanying wobbling small are described in USP 5,138,492.

30 [0008] These conditions are, however, insufficient to be applied to an image pickup system which has a wobbling lens unit placed in a relay lens unit located closer to the image side than the stop and allows insertion/removal of an extender for shifting the focal length to the telephoto side.

35 [0009] More specifically, the conditions described in the above reference are effective for a method of reducing a change in imaging magnification in a state where an optical arrangement behind the stop is fixed, but are not sufficient to be applied to a case wherein the arrangement of an optical system is changed upon insertion/removal of an extender or the like and the incident angle of an off-axis principal ray on a wobbling lens unit, in particular, changes.

SUMMARY OF THE INVENTION

40 [0010] It is an object of the present invention to provide a 4-unit zoom lens which exhibits a small change in imaging magnification accompanying wobbling even with insertion of an optical system such as an extender in the fourth unit serving as a relay lens unit and also exhibits excellent optical performance throughout the entire magnification change range.

45 [0011] In order to achieve the above object, according to the present invention, in a zoom lens in/from which a magnification changing optical unit for changing an overall focal length of the zoom lens can be inserted/removed, a wobbling unit which can be slightly amplitude-driven in an optical axis direction to detect a best imaging position is placed closer to an image side than an insertion position of the magnification changing optical unit.

50 [0012] With this arrangement, a change in imaging magnification caused when the wobbling unit is slightly driven in the optical axis direction can be reduced regardless of insertion/removal of the magnification changing optical unit.

55 [0013] The zoom lens sequentially includes, from an object side, a first unit which is fixed in magnification changing operation and has a positive refractive power, a second unit which moves in the optical axis direction in magnification changing operation and has a negative refractive power, a third unit for correcting an image plane fluctuation accompanying magnification changing operation, and a fourth unit having a positive refractive power for imaging, and a magnification changing optical unit which changes the overall focal length of the zoom lens can be inserted/removed in/from the fourth unit. In this zoom lens, a wobbling unit which can be slightly amplitude-driven in the optical axis direction to detect a best imaging position is placed closer to the image side than the insertion position of the magnification changing optical unit, and a stop for adjustment of light amount is preferably disposed at the object side with respect to the fourth unit.

[0014] More specifically, for example, when the wobbling unit is placed in the fourth unit and amplitude-driven to make an amplitude halfwidth of a backfocus change amount become 1/2 a depth of focus,

$$5 \quad |\alpha_1(S_1 - E_1)/fw_1| < 0.6 \quad (1)$$

is satisfied, where α_1 is an angle of an off-axis sub-principal ray incident on an object-side principal plane of the wobbling unit (without insertion of the magnification changing optical unit), S_1 is a distance to a stop viewed from the object-side principal plane of the wobbling unit (without insertion of the magnification changing optical unit), E_1 is a distance to an image pickup plane viewed from an image-side principal plane of the wobbling unit (without insertion of the magnification changing optical unit), and fw_1 is a focal length at a wide-angle end without insertion of the magnification changing optical unit.

[0015] With this arrangement, a change in imaging magnification accompanying wobbling without insertion of the magnification changing optical unit can be suppressed sufficiently small.

[0016] In addition, when the wobbling unit is placed in the fourth unit amplitude-driven to make an amplitude halfwidth of a backfocus change amount become 1/2 a depth of focus,

$$20 \quad |\alpha_2(S_2 - E_2)/fw_2| < 2.2 \quad (2)$$

is satisfied, where α_2 is an angle of an off-axis sub-principal ray incident on the object-side principal plane of the wobbling unit (with insertion of the magnification changing optical unit), S_2 is a distance to the stop viewed from the object-side principal plane of the wobbling unit (with insertion of the magnification changing optical unit), E_2 is a distance to the image pickup plane viewed from the image-side principal plane of the wobbling unit (with insertion of the magnification changing optical unit), and fw_2 is a focal length at the wide-angle end with insertion of the magnification changing optical unit.

[0017] In addition, in the fourth unit,

$$30 \quad -0.001 < \phi/lm < 0.0015 \quad (3)$$

is satisfied, where ϕ is a refractive power of a lens unit located immediately before the wobbling unit in the fourth unit, and lm is an image size of an image pickup element.

[0018] With this arrangement, a change in incident angle on the wobbling unit upon insertion/removal of the magnification changing optical unit can be made small. This makes it possible to reduce a change in imaging magnification more reliably.

[0019] Further, the amplitude halfwidth of the wobbling unit before/after insertion of the magnification changing optical system is preferably so set as to satisfy the following condition (4).

$$40 \quad \Delta x_2 = F \cdot \Delta x_1 \quad (4)$$

where Δx_1 is an amplitude halfwidth of the wobbling unit before insertion of the magnification changing optical system, Δx_2 is an amplitude halfwidth of the wobbling unit after insertion of the magnification changing optical system, and F is a rate of change of F-number due to insertion/removal of the magnification changing optical system.

[0020] Note that a reduction in the size and weight of the wobbling unit to be slightly amplitude-driven may be attained by placing the wobbling unit closest to the image side in the fourth unit.

[0021] If this system is designed to retract part of the fourth unit from the optical axis by inserting the magnification changing optical unit, a large space for the insertion of the magnification changing optical unit can be ensured while a reduction in the overall size of the zoom lens is attained. This makes it possible to suppress a deterioration in optical performance at the time of insertion of the magnification changing optical unit.

BRIEF DESCRIPTION OF THE DRAWINGS

[0022]

Fig. 1 is a sectional view of a zoom lens according to the first embodiment of the present invention at the wide-

angle end in the first numerical embodiment;

Fig. 2 is a sectional view of a zoom lens according to the first embodiment of the present invention at the wide-angle end in the second numerical embodiment;

Fig. 3 is a sectional view of a zoom lens according to the first embodiment of the present invention at the wide-angle end in the third numerical embodiment;

Fig. 4 is a sectional view of a zoom lens according to the first embodiment of the present invention at the wide-angle end in the fourth numerical embodiment;

Fig. 5 is a sectional view of a zoom lens according to the first embodiment of the present invention at the wide-angle end in the fifth numerical embodiment;

Fig. 6 is a sectional view of a zoom lens according to the first embodiment of the present invention at the wide-angle end in the sixth numerical embodiment;

Fig. 7 is a schematic view showing an optical configuration after the stop of the zoom lens according to the first embodiment (without insertion of an extender);

Fig. 8 is a schematic view showing an optical configuration after the stop of the zoom lens according to the first embodiment (with insertion of the extender);

Fig. 9 is an aberration diagram at the wide-angle end in the first numerical embodiment;

Fig. 10 is an aberration diagram at the telephoto end in the first numerical embodiment;

Fig. 11 is an aberration diagram at the wide-angle end in the second numerical embodiment;

Fig. 12 is an aberration diagram at the telephoto end in the second numerical embodiment;

Fig. 13 is an aberration diagram at the wide-angle end in the fourth numerical embodiment;

Fig. 14 is an aberration diagram at the telephoto end in the fourth numerical embodiment;

Fig. 15 is an aberration diagram at the wide-angle end in the fifth numerical embodiment;

Fig. 16 is an aberration diagram at the telephoto end in the fifth numerical embodiment;

Fig. 17 is an aberration diagram at the wide-angle end in the sixth numerical embodiment;

Fig. 18 is an aberration diagram at the telephoto end in the sixth numerical embodiment;

Fig. 19 is an aberration diagram at the wide-angle end in the first numerical embodiment at the time of insertion of the extender;

Fig. 20 is an aberration diagram at the wide-angle end in the second numerical embodiment at the time of insertion of the extender;

Fig. 21 is an aberration diagram at the wide-angle end in the third numerical embodiment at the time of insertion of the extender;

Fig. 22 is an aberration diagram at the wide-angle end in the fourth numerical embodiment at the time of insertion of the extender;

Fig. 23 is an aberration diagram at the wide-angle end in the fifth numerical embodiment at the time of insertion of the extender;

Fig. 24 is an aberration diagram at the wide-angle end in the sixth numerical embodiment at the time of insertion of the extender;

Fig. 25 is a view showing the arrangement of a photographing system using the zoom lens according to the first embodiment as a photographing optical system; and

Fig. 26 is a view showing a photographing system according to another embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

(First Embodiment)

[0023] Figs. 1 to 6 show the cross-sectional configurations of lenses, of zoom lenses according to the first embodiment of the present invention, which are located at the wide-angle end and infinity focus position in the first to sixth numerical embodiments.

[0024] Referring to Figs. 1 to 6, a first unit (front element) I has a positive refractive power, and a variator II serves as the second unit having a negative refractive power and capable of moving in the optical axis direction in magnification changing operation. The second unit II is monotonously moved to the image side on the optical axis to change the magnification from the wide-angle end to the telephoto end. In magnification changing operation, the second unit II is moved within a range including an imaging magnification of $1\times$ ($-1\times$) (i.e. equal magnification).

[0025] A compensator III serves as the third unit which can move in the optical axis direction to correct an image plane fluctuation accompanying magnification changing operation.

[0026] A stop SP is used for light amount adjustment. A fourth unit IV having a positive refractive power is used for imaging.

[0027] A glass block G is a color separation prism, optical filter, or the like. A wobbling unit wo can be slightly am-

plitude-driven in the optical axis direction to detect the best imaging position. A lens unit L4b is placed immediately before the wobbling unit in the fourth unit.

[0028] An extender (magnification changing optical unit) EX for increasing or decreasing the overall focal length of the zoom lens system can be inserted/removed (or mounted/dismounted) in/from the space in the fourth unit.

[0029] In this embodiment, the configuration of a lens unit (to be referred to as a relay unit hereinafter) located closer to the image side than the stop SP is properly set such that a change in imaging magnification accompanying wobbling of the wobbling unit wo is reduced regardless of whether the extender EX is inserted/removed.

[0030] The wobbling unit wo needs to be amplitude-driven at high speed in the optical axis direction. It is therefore preferable that the wobbling unit wo have a proper backfocus sensitivity degree and be light in weight. A zoom lens for a TV set needs to have a long backfocus and a small F-number, and hence requires many lenses constituting each unit. In addition, each lens has a large effective diameter, and an extender, macro photographing mechanism, flange-back adjustment mechanism, and the like must be arranged in the relay unit, resulting in a low degree of freedom in placing the wobbling unit.

[0031] Figs. 7 and 8 schematically show lens units behind the stop SP. Fig. 7 shows a state where the extender EX is not inserted. Fig. 8 shows a state where the extender EX is inserted. Referring to Fig. 8, the magnification of the extender EX is set to 2 \times , and an image is enlarged by 2 \times on an image plane.

[0032] Referring to Fig. 7, an image height change ratio can be expressed as follows. Letting α_1 be the incident angle of sub-principal ray on the wobbling unit wo, ϕ_{wo} be the power of the wobbling unit wo, S_1 be the distance between the wobbling unit wo and an image plane, ϕ_{4c} be the power of lens unit L4c located closer to the image side than the wobbling unit wo, Δx be the wobbling amount, $(S_1 - E_1)$ be the difference between the distance to a virtual image of the stop SP viewed from the wobbling unit wo and the distance to a virtual image of the image plane viewed from the wobbling unit wo, and Δy be the image height change amount at the time of wobbling, an image height change ratio $\Delta y/fw$ (where fw is the focal length of the overall system at the wide-angle end) can be expressed by

$$\frac{\Delta y}{f_w} = \alpha_1 \cdot \phi_{wo} \cdot (S_1 \phi_{4c} - 1) \cdot \Delta x \cdot \{ \Delta x - (S_1 - E_1) \} \cdot \frac{1}{f_w}$$

[0033] The wobbling amount Δx is a sufficiently small value relative to $(S_1 - E_1)$, and hence can be expressed by

$$\frac{\Delta y}{f_w} = \alpha_1 \cdot (S_1 \phi_{4c} - 1) \cdot (S_1 - E_1) \cdot \frac{1}{f_w}$$

[0034] In the configuration of the zoom lens according to this embodiment, parameters that change upon insertion/removal of the extender EX and have great influences on the image height change ratio $\Delta y/fw$ are the incident angle α_1 of a principal ray on the wobbling unit wo and $(S_1 - E_1)$.

[0035] The allowable value of the wobbling amount Δx will be described. It is said that the resolution of the visual sense of a person having 20/20 vision is about one minute. If, for example, the person watches a 30-inch TV screen (having a screen size of about 50 cm in the horizontal direction) at a distance of 2.5 m, the viewing angle in the horizontal direction becomes about 680 minutes. A resolution of one minute therefore corresponds to 0.15% of the screen.

[0036] If the lens is stopped down, the depth of focus increases as compared with that at full aperture. In addition, a larger wobbling amount is required to detect the best focus position, and hence the image height change ratio increases.

[0037] In consideration of the fact that the highest frequency in use of an F-number range is about full aperture: F/5.6, an image height change ratio is allowed at most 0.15% at F/5.6. An allowable value at full aperture (F/1.752) becomes about 0.06% which is about 1/3 the image height change ratio at F/5.6. The upper limit of conditional expression (1) is determined such that the image height change ratio at full aperture (F/1.752) falls within an image height change ratio of 0.06% (0.15% at F/5.6), and falls within the allowable range even if the image height change ratio changes upon insertion of the extender EX.

[0038] The relationship between the wobbling amount Δx and the change amount in backfocus Δsk is expressed by

$$\Delta x = \frac{\Delta sk}{(1 - \beta_1^2) \cdot \beta_2^2}$$

where β_1 is a lateral magnification of the wobbling unit, and β_2 is a lateral magnification of an optical system placed at the image side with respect to the wobbling unit. When the change amount in backfocus Δsk is 1/2 the depth

of focus, the relationship between the change amount in backfocus Δsk and the F-number fno is expressed by

$$\Delta sk = \delta \cdot fno/2$$

5 where δ is a permissible circle of confusion determined by the camera system.

[0039] In the present invention, the wobbling lens unit is disposed closer to the image side than the magnification changing optical unit capable of being inserted and removed, so that the wobbling amount Δx has a relation proportional to the F-number since both β_1 and β_2 are constant before/after insertion of the magnification changing optical system.

[0040] Considering the wobbling amount after insertion of a 2X extender, since the F-number becomes doubled, the depth of focus also becomes doubled. The amplitude driving amount of the wobbling unit must also be doubled.

[0041] The F-number in practical use at the time of insertion of the 2x extender falls within a narrow range of about F/4 to F/5.6 because the F-number at the full aperture end increases. For this reason, if a maximum of 0.15% of the value at F/5.6 is allowed at the time of insertion of the extender, the allowable amount at full aperture (F/4) becomes about 0.1%. That is, an allowable amount as large as double the value before the insertion of the extender can be allowed.

[0042] The allowable upper limit value of an image height change ratio indicated by conditional expressions (1) and (2) is the value set when the wobbling unit is amplitude-driven in the optical axis direction such that the amplitude halfwidth of a change in backfocus becomes 1/2 the depth of focus. In practice, this value changes depending on the manner of determining a wobbling amount with respect to the depth of focus (e.g., setting the amplitude halfwidth to 1/3 the depth of focus or to be equal to it), an assumed screen size, and the like.

[0043] Considering a system frequency using F-numbers equal to or larger than F/5.6 or setting of smallerfull aperture F-numbers, a system is required in which the image height change ratio at full aperture is further suppressed and a change before/after insertion of an extender is smaller.

[0044] Consider only a state where no extender is inserted. In this case, to reduce a change in imaging magnification accompanying wobbling, the incident angle α_1 of a sub-principal ray on the wobbling unit and the difference ($S_1 - E_1$) between the distance E_1 to the stop viewed from the wobbling unit and the distance S_1 to the image plane viewed from the wobbling unit must be reduced.

[0045] When the extender EX in the state shown in Fig. 7 is inserted (Fig. 8), the incident angle of sub-principal ray on the wobbling unit w_0 changes to α_2 , and a distance E_2 to the stop SP viewed from the wobbling unit w_0 changes. However, a distance S_2 to the image plane viewed from the wobbling unit w_0 is almost constant ($S_2 \approx S_1$) regardless of insertion/removal of the extender, and hence a change in imaging magnification at the time of insertion of the extender remains.

[0046] In order to reduce a change in imaging magnification accompanying wobbling in a state where the extender is not inserted, the following condition must be satisfied:

$$0.05 < |\alpha_1(S_1 - E_1)/fw_1| < 0.6 \quad (1)$$

[0047] With approach to the lower limit value of conditional expression (1), a change in imaging magnification while the extender is not inserted is reduced, and an ideal condition is obtained.

[0048] While the extender is inserted, it is difficult to cancel out the distance E_2 with respect to the distance S_2 in Fig. 8, and a change in imaging magnification remains. This condition is not necessarily a desired condition for an optical system in/from which the extender is inserted/removed.

[0049] If the upper limit value is exceeded, a change in imaging magnification without insertion of the extender is large. It indicates that this condition is not suitable for wobbling.

[0050] Therefore, while the extender is inserted, the following is preferably satisfied:

$$0.05 < |\alpha_2(S_2 - E_2)/fw_2| < 2.2 \quad (2)$$

[0051] If the upper limit value of this conditional expression (2) is exceeded, it indicates that a change in imaging magnification at the time of insertion/removal of the extender is large.

[0052] In addition, the refractive power ϕ_{4b} of the lens unit L4b located immediately before the wobbling unit w_0 in the fourth unit IV preferably satisfies

$$-0.001 < \phi_{4b}/lm < 0.0015 \quad (3)$$

where l_m is the image size of the image pickup element.

[0053] If the positive or negative refractive power of the lens unit L4b is increased beyond the range of conditional expression (3), the incident angle of a principal ray on the wobbling unit wo greatly changes from α_1 to α_2 or from α_2 to α_1 , and a change in imaging magnification becomes large under one of the conditions.

[0054] It is preferable to set the amplitude amount of the wobbling unit to the following condition (4) before/after insertion of the magnification changing optical system.

$$\Delta x_2 = F \cdot \Delta x_1 \quad (4)$$

where Δx_1 is an amplitude halfwidth of the wobbling unit before insertion of the magnification changing optical system, Δx_2 is an amplitude halfwidth of the wobbling unit after insertion of the magnification changing optical system, and F is a rate of change of F-number due to insertion/removal of the magnification changing optical system. This enables the best focus position to be detected and a system in which blur is not conspicuous on a screen upon detection to be provided irrespective of whether the magnification changing optical system is inserted or not.

<<Numerical Embodiments>>

[0055] The numerical embodiments of this embodiment will be described below. In the numerical embodiments 5 to 6, let r_i be the radius of curvature of the i th lens from the object side, d_i be the thickness or air gap of the i th optical member from the object side, and n_i and v_i ("v" in the tables) be the refractive index and Abbe number, respectively, of the glass of the i th lens from the object side with respect to a d line.

[0056] Letting the X-axis be the optical axis direction, the H-axis be a direction perpendicular to the optical axis, a traveling direction of light be positive, R be the paraxial radius of curvature, and B , C , D , and E be aspherical coefficients, an aspherical shape is expressed by

$$X = \frac{(1/R)H^2}{1 + \sqrt{1 - (H/R)^2}} + BH^4 + CH^6 + DH^8 + EH^{10}$$

(Numerical Embodiment 1)

[0057]

TABLE 1

Numerical Embodiment 1			
$f = 9.50 \sim 185.25$ Fno: 1.85 ~ 2.85 2ω: 60.1° ~ 3.4°			
$r_1 = 600.261$	$d_1 = 2.20$	$n_1 = 1.76168$	$v_1 = 27.5$
$r_2 = 81.461$	$d_2 = 11.42$	$n_2 = 1.49845$	$v_2 = 81.6$
$r_3 = -290.956$	$d_3 = 7.63$	$n_3 = 1.62287$	$v_3 = 60.3$
$r_4 = 86.701$	$d_4 = 7.86$	$n_4 = 1.73234$	$v_4 = 54.7$
$r_5 = 3044.710$	$d_5 = 0.15$	$n_5 = 1.88814$	$v_5 = 40.8$
$r_6 = 66.016$	$d_6 = 6.01$	$n_6 = 1.82017$	$v_6 = 46.6$
$r_7 = 145.708$	$d_7 = \text{Variable}$	$n_7 = 1.81264$	$v_7 = 25.4$
$r_8 = 111.445$	$d_8 = 0.80$	$n_8 = 1.79196$	$v_8 = 47.4$
$r_9 = 16.812$	$d_9 = 4.65$	$n_9 = 1.74679$	$v_9 = 49.3$
$r_{10} = -47.842$	$d_{10} = 0.70$	$n_{10} = 1.85501$	$v_{10} = 23.9$
$r_{11} = 33.779$	$d_{11} = 2.24$		
$r_{12} = 28.944$	$d_{12} = 5.20$		
$r_{13} = -29.192$	$d_{13} = 0.54$		
$r_{14} = -24.664$	$d_{14} = 0.70$		
$r_{15} = 132.572$	$d_{15} = \text{Variable}$		
$r_{16} = -28.806$	$d_{16} = 0.75$		
$r_{17} = 37.218$	$d_{17} = 3.81$		
$r_{18} = 449.023$	$d_{18} = \text{Variable}$		

TABLE 1 (continued)

Numerical Embodiment 1			
r19= ∞ (stop)	d19= 1.80	n11= 1.67340	v11= 47.2
r20= -231.233	d20= 3.33		
r21= -49.133	d21= 0.20	n12= 1.51976	v12= 52.4
r22= -170.365	d22= 4.05		
r23= -38.625	d23= 0.20	n13= 1.48915	v13= 70.2
r24= 36.315	d24= 10.16	n14= 1.83932	v14= 37.2
r25= -35.564	d25= 1.66		
r26= 0.000	d26= 36.00	n15= 1.50349	v15= 56.4
r27= 97.385	d27= 6.36		
r28= -44.438	d28= 0.20	n16= 1.83932	v16= 37.2
r29= -535.654	d29= 1.40	n17= 1.50349	v17= 56.4
r30= 21.016	d30= 7.22		
r31= -424.093	d31= 1.50	n18= 1.62033	v18= 58.9
r32= 38.505	d32= 8.29	n19= 1.77621	v19= 49.6
r33= -27.482	d33= 1.40		
r34= 91.360	d34= 0.30	n20= 1.53430	v20= 48.8
r35= 38.429	d35= 6.84		
r36= -52.407	d36= 5.00	n21= 1.60718	v21= 38.0
r37= ∞	d37= 30.00	n22= 1.51825	v22= 64.2
r38= ∞	d38= 16.20		
r39= ∞			

TABLE 2

Extender Portion			
	d26= 1.60		
r27= 64.675	d27= 6.74	n15= 1.49845	v15= 81.5
r28= -54.795	d28= 0.20		
r29= 25.068	d29= 6.49	n16= 1.49845	v16= 81.5
r30= -128.700	d30= 0.80	n17= 1.85501	v17= 23.9
r31= 56.237	d31= 11.25		
r32= -106.936	d32= 0.90	n18= 1.64254	v18= 60.1
r33= 10.653	d33= 2.65	n19= 1.85501	v19= 23.9
r34= 14.647	d34= 5.37		

Focal Length Variable Interval	9.50	38.00	185.25
d 7	0.65	35.60	52.03
d 15	53.76	13.79	6.32
d 18	5.10	10.11	1.15

[D058] In the numerical embodiment 1 shown in Fig. 1, to reduce variations in optical performance upon insertion of

the extender EX, the extender EX is preferably placed in a substantially afocal parallel light beam. In addition, a wide gap is required to satisfy the extender magnification requirement and optical performance requirement.

[0059] As a wobbling unit which satisfies conditional expression (1), has a proper backfocus sensitivity degree accompanying slight amplitude driving of the wobbling unit w_0 , and exhibits a small change in imaging magnification, all or some of lens units located closer to the image side than the extender EX are preferably used.

[0060] In the numerical embodiment 1, three lenses of which form two units in the fourth unit and are located closest to the image side, are used as wobbling unit lenses. By making some lenses of the fourth unit movable, a reduction in the weight of the wobbling unit w_0 is achieved. In addition, by setting the refractive power of the lens unit L4b located immediately before the wobbling unit within the range of conditional expression (3), a change in imaging magnification is small regardless of the presence/absence of the extender EX.

[0061] In the numerical embodiment 1, the extender EX can be inserted/removed in/from a space with gap d26 = 36 mm.

[0062] Table 12 shows the numerical values of conditional expressions and imaging magnification change ratios in the respective numerical embodiments. Each imaging magnification change ratio is the value obtained when wobbling is performed upon setting the amplitude halfwidth to 1/2 the depth of focus at the full aperture end.

[0063] If, for example, the permissible circle of confusion of a 2/3-inch CCD (image size: $\phi 11$ mm) which is the mainstream in TV cameras is set to about 0.021 mm, the depth of focus at F/2 becomes about 0.04 mm.

[0064] Figs. 9 and 10 are aberration diagrams at the wide-angle end and telephoto end without insertion of the extender in the first numerical embodiment. Fig. 19 is an aberration diagram at the wide-angle end with insertion of

Extender in the first numbered embodiment. Fig. 10 is an elevation diagram of the truss angle end with insertion of the extender.

(Numerical Embodiment 2)

[0065]

TABLE 3

Numerical Embodiment 2			
$f = 9.50 \sim 185.25$ Fno: 2.0 ~ 2.85 2 ω : 60.1° ~ 3.4°			
r 1= 622.723	d 1= 2.20	n 1= 1.76168	v 1= 27.5
r 2= 77.855	d 2= 12.34	n 2= 1.48915	v 2= 70.2
r 3= -323.998	d 3= 7.78		
r 4= 86.923	d 4= 8.56	n 3= 1.62032	v 3= 63.4
r 5= -1529.464	d 5= 0.15		
r 6= 64.688	d 6= 6.06	n 4= 1.73234	v 4= 54.7
r 7= 134.784	d 7= Variable		
r 8= 111.445	d 8= 0.80	n 5= 1.88814	v 5= 40.8
r 9= 16.812	d 9= 4.65		
r10= -47.842	d10= 0.70	n 6= 1.82017	v 6= 46.6
r11= 33.779	d11= 2.24		
r12= 28.944	d12= 5.20	n 7= 1.81264	v 7= 25.4
r13= -29.192	d13= 0.54		
r14= -24.664	d14= 0.70	n 8= 1.79196	v 8= 47.4
r15= 132.572	d15= Variable		
r16= -28.806	d16= 0.75	n 9= 1.74679	v 9= 49.3
r17= 37.218	d17= 3.81	n10= 1.85501	v10= 23.9
r18= 449.023	d18= Variable		
r19= ∞ (Stop)	d19= 1.40		
r20= -1109.872	d20= 4.46	n11= 1.67340	v11= 47.2
r21= -30.372	d21= 0.20		
r22= 104.731	d22= 6.31	n12= 1.48915	v12= 70.2
r23= -26.574	d23= 1.20	n13= 1.83932	v13= 37.2
r24= -74.569	d24= 30.00		
r25= 170.165	d25= 3.69	n14= 1.48915	v14= 70.2
r26= -86.018	d26= 2.50		

TABLE 3 (continued)

Numerical Embodiment 2			
r27= 46.559	d27= 4.04	n15=1.69979	v15= 55.5
r28= 178.870	d28= 6.00		
r29= -66.299	d29= 1.20	n16=1.08815	v16= 40.8
r30= 151.817	d30= 7.03	n17=1.48915	v17= 70.2
r31= -37.731	d31= 0.15		
r32= 74.679	d32= 1.20	n18=1.80642	v18= 35.0
r33= 28.773	d33= 4.28		
r34= 78.908	d34= 8.64	n19=1.52033	v19= 58.9
r35= -20.059	d35= 1.20	n20=1.88815	v20= 40.8
r36= -66.519	d36= 4.03		
r37= 1248.781	d37= 4.71	n21=1.66152	v21= 50.9
r38= -35.175	d38= 4.00		
r39= ∞	d39= 30.00	n22=1.60718	v22= 38.0
r40= ∞	d40= 16.20	n23=1.51825	v23= 64.2
r41= ∞			

TABLE 4

Extender Portion			
d24= 1.60			
r25= -377.563	d25= 2.81	n14=1.52033	v14= 58.9
r26= -49.635	d26= 0.20		
r27= 19.162	d27= 5.72	n15=1.51976	v15= 52.4
r28= 96.555	d28= 0.20		
r29= 15.020	d29= 5.62	n16=1.51825	v16= 64.1
r30= 137.066	d30= 0.80	n17=1.85501	v17= 23.9
r31= 10.484	d31= 6.63		
r32= -49.330	d32= 0.90	n18=1.64254	v18= 60.1
r33= 11.941	d33= 2.99	n19=1.85501	v19= 23.9
r34= 30.819	d34= 2.67		

Focal Length Variable Interval	9 . 50	38 . 00	185 . 25
d 7	1 . 08	36 . 03	52 . 46
d 15	53 . 75	13 . 79	6 . 32
d 18	5 . 10	10 . 11	1 . 15

[0066] In the numerical embodiment 2 shown in Fig. 2, the second lens located closer to the image side than the insertion gap of the extender EX is used as a wobbling unit lens. The extender EX can be inserted/removed in/from a space with d24 = 30 mm.

[0067] Since the positive refractive power ϕ_{4b} of the lens unit L4b located immediately before the wobbling unit wo is brought near to the upper limit in the numerical embodiment 1, a change (conditional expression (2)) in imaging magnification upon insertion/removal of the extender takes a large value.

[0068] The lens unit L4c constituted by six lenses which form four units in the fourth unit and are located closer to the image side than the wobbling unit wo are constituted by two lens units L4c1 and L4c2. In addition, the use of the lens unit L4c2 allows macro photographing for proximity photographing and flange-back adjustment for adjusting the dimensional error between the reference surface of a lens (flange surface) and an image plane in a lens-interchangeable camera, independently of the main focusing lens.

[0069] Figs. 11 and 12 are aberration diagrams at the wide-angle end and telephoto end without insertion of the extender in the numerical embodiment 1. Fig. 20 is an aberration diagram at the wide-angle end with insertion of the extender.

10 (Numerical Embodiment 3)

[0070]

TABLE 5

Numerical Embodiment 3				
Extender Portion				
r25= 722.998	d24= 1.60	n14=1.52033	v14= 58.9	
r26= -69.098	d25= 3.37			
r27= 21.904	d26= 0.20	n15=1.51976	v15= 52.4	
r28= 156.887	d27= 5.85			
r29= 17.349	d28= 0.20	n16=1.51825	v16= 64.1	
r30= 117.012	d29= 5.19	n17=1.85501	v17= 23.9	
r31= 12.697	d30= 0.80			
r32= 378.277	d31= 8.57	n18=1.64254	v18= 60.1	
r33= 12.453	d32= 0.90	n19=1.85501	v19= 23.9	
r34= 25.927	d33= 3.62			
	d34= 6.00			

[0071] In contrast to the lens system in the numerical embodiment 2, in the numerical embodiment 3 shown in Fig. 3, the extender can be inserted in the space with d24 to d26 by retracting (ejecting) part (L4b) of the fourth unit from the optical axis at the time of insertion of the extender EX. By retracting part of the fourth unit, a reduction in the space for insertion/removal of the extender can be attained. This makes it possible to achieve a reduction in the size of the lens system and suppress a deterioration in optical performance at the time of insertion of the extender by effectively using the wide space.

[0072] Even in a case where part of the fourth unit is retracted at the time of insertion of the extender, an appropriate imaging magnification change ratio can be kept by properly setting the refractive power of the lens unit L4b.

[0073] Fig. 21 is an aberration diagram at the wide-angle end at the time of insertion of the extender in the numerical embodiment 3.

(Numerical Embodiment 4)

[0074]

TABLE 6

Numerical Embodiment 4				
$f=9.50 \sim 185.25$ Fno:2.0~2.85 2ω:60.1° ~3.4°				
r 1= 622.723	d 1= 2.20	n 1=1.76168	v 1= 27.5	
r 2= 77.855	d 2= 12.34	n 2=1.48915	v 2= 70.2	
r 3= -323.998	d 3= 7.78			
r 4= 86.923	d 4= 8.66	n 3=1.62032	v 3= 63.4	
r 5= -1529.464	d 5= 0.15			
r 6= 64.688	d 6= 6.06	n 4=1.73234	v 4= 54.7	
r 7= 134.784	d 7= Variable			

TABLE 6 (continued)

Numerical Embodiment 4			
r 8= 111.446	d 8= 0.80	n 5=1.88814	v 5= 40.8
r 9= 16.812	d 9= 4.65		
r10= -47.842	d10= 0.70	n 6=1.82017	v 6= 46.6
r11= 33.779	d11= 2.24		
r12= 28.944	d12= 5.20	n 7=1.81264	v 7= 25.4
r13= -29.192	d13= 0.54		
r14= -24.664	d14= 0.70	n 8=1.79196	v 8= 47.4
r15= 132.572	d15=Variable		
r16= -28.806	d16= 0.75	n 9=1.74579	v 9= 49.3
r17= 37.218	d17= 3.81	n10=1.85501	v10= 23.9
r18= 449.023	d18=Variable		
r19= ∞ (Stop)	d19= 1.40		
r20= -167.968	d20= 4.19	n11=1.66152	v11= 50.9
r21= -28.839	d21= 0.20		
r22= 216.499	d22= 2.57	n12=1.48915	v12= 70.2
r23= -159.531	d23= 0.00		
r24= 88.815	d24= 6.34	n13=1.48915	v13= 70.2
r25= -29.606	d25= 1.20	n14=1.83932	v14= 37.2
r26= -76.274	d26= 30.00		
r27= 59.688	d27= 1.20	n15=1.48915	v15= 70.2
r28= 35.023	d28= 2.50		
r29= 43.898	d29= 4.98	n16=1.69979	v16= 55.5
r30= -79.430	d30= 2.50		
r31= -46.969	d31= 1.20	n17=1.88815	v17= 40.8
r32= 72.323	d32= 7.79	n18=1.48915	v18= 70.2
r33= -28.720	d33= 0.15		
r34= 129.989	d34= 1.20	n19=1.80642	v19= 35.0
r35= 29.797	d35= 3.71		
r36= 66.767	d36= 9.33	n20=1.51976	v20= 52.4
r37= -17.449	d37= 1.20	n21=1.88815	v21= 40.8
r38= -49.582	d38= 3.79		
r39= 819.738	d39= 4.62	n22=1.66152	v22= 50.9
r40= -31.246	d40= 4.00		
r41= ∞	d41= 30.00	n23=1.60718	v23= 38.0
r42= ∞	d42= 16.20	n24=1.51825	v24= 64.2
r43= ∞			

TABLE 7

Extender Portion			
r27= 746.348	d26= 1.60	n15=1.48915	v15= 70.2
r28= -55.871	d27= 3.32		
r29= 16.521	d28= 0.20		
r30= 36.028	d29= 5.27	n16=1.49845	v16= 81.5
r31= 13.452	d30= 0.20		
r32= 31.044	d31= 4.96	n17=1.51825	v17= 64.1
r33= 9.442	d32= 0.80	n18=1.85501	v18= 23.9
r34= -37.409	d33= 7.64		
	d34= 0.90	n19=1.75844	v19= 52.3

TABLE 7 (continued)

Extender Portion			
r35= 11.531	d35= 3.17	n20= 1.85501	v20= 23.9
r36= 45.968	d36= 1.97		

Focal Length Variable Interval	9.50	38.00	185.25
d 7	1.08	36.03	52.46
d 15	53.75	13.79	6.32
d 18	5.10	10.11	1.15

[0075] In the numerical embodiment 4 shown in Fig. 4, the second lens located closer to the image side than the insertion gap for the extender EX is used as a wobbling unit lens. In addition, the extender EX can be inserted in a space with d26 = 30 mm.

[0076] In the numerical embodiment 4, the lens unit L4b located closer to the object side than the wobbling unit wo has a negative refractive power. In contrast to the numerical embodiment 1, since $\phi 4b$ is brought closer to the lower limit, a change in imaging magnification (conditional expression (2)) accompanying insertion of the extender EX takes a large value.

[0077] Figs. 13 and 14 are aberration diagrams at the wide-angle end and telephoto end without insertion of the extender in the numerical embodiment 4. Fig. 22 is an aberration diagram at the wide-angle end with insertion of the extender.

(Numerical Embodiment 5)

[0078]

TABLE 8

Numerical Embodiment 5				
$f=9.50 \sim 185.25$ Fno:2.0~2.85 2ω:60.1° ~3.4°				
r 1= 622.723	d 1= 2.20	n 1= 1.76168	v 1= 27.5	
r 2= 77.855	d 2= 12.34	n 2= 1.48915	v 2= 70.2	
r 3= -323.998	d 3= 7.78			
r 4= 86.923	d 4= 8.66	n 3= 1.62032	v 3= 63.4	
r 5= -1529.464	d 5= 0.15			
r 6= 64.688	d 6= 6.06	n 4= 1.73234	v 4= 54.7	
r 7= 134.784	d 7= Variable			
r 8= 111.445	d 8= 0.80	n 5= 1.88814	v 5= 40.8	
r 9= 16.812	d 9= 4.65			
r10= -47.842	d10= 0.70	n 6= 1.82017	v 6= 46.6	
r11= 33.779	d11= 2.24			
r12= 28.944	d12= 5.20	n 7= 1.81264	v 7= 25.4	
r13= -29.192	d13= 0.54			
r14= -24.664	d14= 0.70	n 8= 1.79196	v 8= 47.4	
r15= 132.572	d15= Variable			
r16= -28.806	d16= 0.75	n 9= 1.74679	v 9= 49.3	
r17= 37.218	d17= 3.81	n10= 1.85501	v10= 23.9	

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TABLE 8 (continued)

Numerical Embodiment 5			
r18= 449.023	d18=Variable		
r19= ∞ (Stop)	d19= 1.40	n11= 1.66152	v11= 50.9
r20= -288.753	d20= 4.45		
r21= -27.952	d21= 0.20	n12= 1.48915	v12= 70.2
r22= 64.233	d22= 7.14	n13= 1.83932	v13= 37.2
r23= -25.959	d23= 1.20		
r24= -72.322	d24= 30.00	n14= 1.48915	v14= 70.2
r25= 47.982	d25= 5.34		
r26= -125.570	d26= 2.50	n15= 1.69979	v15= 55.5
r27= -96.426	d27= 1.20		
r28= 191.570	d28= 5.00	n16= 1.88815	v16= 40.8
r29= -122.237	d29= 1.20	n17= 1.48915	v17= 70.2
r30= 1090.682	d30= 5.32		
r31= -30.494	d31= 0.15	n18= 1.80642	v18= 35.0
r32= 106.004	d32= 1.20		
r33= 34.262	d33= 2.67	n19= 1.50349	v19= 56.4
r34= 47.028	d34= 8.44	n20= 1.88815	v20= 40.8
r35= -20.185	d35= 1.20		
r36= -76.910	d36= 2.56	n21= 1.66152	v21= 50.9
r37= 90.563	d37= 4.83		
r38= -49.369	d38= 4.00	n22= 1.60718	v22= 38.0
r39= ∞	d39= 30.00		
r40= ∞	d40= 16.20	n23= 1.51825	v23= 64.2
r41= ∞			

TABLE 9

Extender Portion			
r25= 1327.342	d24= 1.60	n14= 1.52033	v14= 58.9
r26= -65.631	d25= 2.96		
r27= 19.393	d26= 0.20	n15= 1.52033	v15= 58.9
r28= 92.908	d27= 5.95		
r29= 16.264	d28= 0.20	n16= 1.51825	v16= 64.1
r30= 88.347	d29= 5.90	n17= 1.85501	v17= 23.9
r31= 10.562	d30= 0.80		
r32= -61.482	d31= 6.15	n18= 1.64254	v18= 60.1
r33= 11.288	d32= 0.90		
r34= 24.985	d33= 2.81	n19= 1.85501	v19= 23.9
	d34= 2.54		

50

55

Variable Interval	Focal Length	9.50	38.00	185.25
d 7	1.08	36.03	52.46	
d 15	53.75	13.79	6.32	
d 18	5.10	10.11	1.15	

- [0079] In the numerical embodiment 5 shown in Fig. 5, the second lens located closer to the image side than the insertion gap for the extender EX is used as a wobbling unit lens, and the extender EX can be inserted/removed in/from a space with $d_{24} = 30$ mm. In the numerical embodiment 5, the wobbling unit wo has a negative refractive power.
- [0080] In the numerical embodiment 5, ϕ_4b is brought closer to the upper limit, a change in imaging magnification (conditional expression (2)) accompanying insertion/removal of the extender takes a large value.
- [0081] In this numerical embodiment, the unit L4c is integrally moved to allow macro photographing and flange-back adjustment.
- [0082] Figs. 15 and 16 are aberration diagrams at the wide-angle end and telephoto end without insertion of the extender in the numerical embodiment 5. Fig. 23 is an aberration diagram at the wide-angle end with insertion of the extender.

(Numerical Embodiment 6)

[0083]

TABLE 10

Numerical Embodiment 6			
$f=10.0 \sim 440.0$ Fno:1.75~3.0 2ω:57.6° ~1.4°			
r 1= 370.170	d 1= 5.50	n 1=1.72311	v 1= 29.6
r 2= 179.081	d 2= 0.47		
r 3= 177.086	d 3= 21.52	n 2=1.43496	v 2= 95.1
r 4= -738.246	d 4= 0.30		
r 5= 179.834	d 5= 16.94	n 3=1.43496	v 3= 95.1
r 6=-18484.366	d 6= 0.30		
r 7= 136.803	d 7= 11.61	n 4=1.49845	v 4= 81.6
r 8= 299.938	d 8=Variable		
r 9= 2064.706	d 9= 2.00	n 5=1.32017	v 5= 46.6
r10= 56.194	d10= 4.93		
r11= -200.836	d11= 1.80	n 6=1.77621	v 6= 49.6
r12= 58.527	d12= 5.92		
r13= -70.671	d13= 1.80	n 7=1.82017	v 7= 46.6
r14= 47.059	d14= 7.61	n 8=1.93306	v 8= 21.3
r15= -741.457	d15=Variable		
r16= -3286.091	d16= 6.09	n 9=1.50014	v 9= 65.0
r17= -100.506	d17= 0.30		
r18= 101.499	d18= 2.50	n 10=1.65223	v10= 33.8
r19= 80.299	d19= 11.32	n 11=1.59143	v11= 61.2
r20= -160.387	d20= 0.20		
r21= 153.942	d21= 11.39	n 12=1.60548	v12= 60.7
r22= -78.774	d22= 2.50	n 13=1.85501	v13= 23.9